

SaveBuild (F7)Download (F8)Change to blocksModeViewer

schoolkits.h

```
motor(2, DIR_CCW, 15);
delay(100);
off(OUT3);
break;
}
}
}
else
{
  if(IN1)
  {
    switch(getRemocon())
    {
      case 0x04: // IR Remocon8Key, port7
        motor(0, DIR_CCW, 15);
        motor(2, DIR_CCW, 15);
        delay(100);
        off(OUT3);
        break;
    }
  }
  else
  {
    switch(getRemocon())
    {
      case 0x08: // IR Remocon8Key, port7
        motor(0, DIR_CCW, 0);
        motor(2, DIR_CCW, 0);
        delay(100);
        off(OUT1);
        break;
    }
  }
}
}
}
end();
return 0;
```

FunctionsNew

Chips10CL

Delay

While

If Else

Sensors

1-3

IR Sensor

Port1:ON

IF Port1

YES

NO

IR, R/C 8

1

DC Motor

F F

Delay

0.1

Off

1

End If

End If

IF Port1

YES

NO

IR, R/C 8

2

DC Motor

F B

Delay

0.1

Off

3

End If

End If

IF Port1

YES

NO

IR, R/C 8

3

DC Motor

B F

Delay

0.1

Off

3

End If

End If

IF Port1

YES

NO

IR, R/C 8

4

DC Motor

0 0

Delay

0.1

Off

1

End If

End If

Function

10CL



